<u>Cost effective</u> <u>overload protection</u>

OPTI torque

Ball/detent torque limiter

- Accurate, reliable torque control
- Wide torque range
- Unique system for setting torque



K.460.V06.GB



Why use a torque limiter?

The concept:

A torque limiter is a mechanical device that disengages when the transmitted torque exceeds a pre-set value, i.e. when an overload occurs.

People, products, drives, equipment and machines can be protected against the damage caused by overloads, and the costly repairs and unnecessary downtime which can result.

Compared to an overcurrent relay, or other electrical overload devices a torque limiter not only provides a signal in the event of an overload, but instantaneously disengages, isolating the inertia energy of the drive system.

OPTI torque increases productivity by eliminating expensive machine downtime.

The practical solution:

Many years of experience developing, improving and manufacturing torque limiting clutches enable us to now offer the ideal mechanical torque limiter for virtually every application. The latest production techniques and quality control systems guarantee consistently high quality products that are economically priced.



Only OPTI torque offers all the following advantages

- * OPTI torque assures precise torque contol. Even in extreme conditions, repetitive accuracies of +/-5% are achieved.
- * The OPTI torque system of differing spring weights and configurations results in wide torque ranges for all size units. Low torque applications with large shaft diameters are possible.
- * OPTI torque's small size yields low mass moments of inertia.
- * OPTI torque offers a unique system for setting the overload torque, making adjustment both easy and accurate.
- * OPTI torque features a positive locking arrangement, preventing torque setting changes during operation.
- * OPTI torque's large diameter limit switch plate allows the use of commercially available, inexpensive limit switch (see page 11). Promixity sensors can be used without limit switch plate installed.

Engineering Assistance

Please let us know what your specific requirements are und we will be happy to work out, without any obligation, a detailed recommendation. Since our engineers cannot be aware of all applications and control all factors that may affect the function of our products, our warranty applies only to products manufactured by Mayr.

In accordance with our established policy to constantly improve our products, the specifiations contained herein are subject to change without notice.

Basic function of OPTI torque:

OPTI torque is a "ball/roller detent torque limiting clutch", transmitting torque via balls and detents (multiple position reset) or rollers are held in their respective detents through the pressure generated by disc springs. When an overload occurs, exceeding the pre-set torque, the balls or rollers ride out of their detents, disengaging the clutch.

The balls or rollers riding out of their detents produce the axial stroke of the limit switch plate, which is used to actuate a mechanical limit switch to shut down the drive. Alternatively, the OPTI torque can be used without a limit switch plate and a proximity switch sensing the axial movement of the control element.

The limiting torque for an overload is set by adjusting the spring pressure on the balls or rollers. This is done by means of an adjusting nut, which is positively locked once the torque has been set. As OPTI torque utilizes rolling disengagement, torque changes due to frictional wear, as in friction type torque limiters, are eliminated. Consistent and repeatable torque settings, unaffected by outside influences such as temperature, humidity or lubrication are the result.

Options and special designs:

Double "C" face or IEC-flange torque limiter. For installation between motor and gear box.

Design for small drive elements.

Covered and sealed units for dusty environments or severe conditions, such as high pressure wash down.

Optional finishes

OPTI torque standard finish is zinc phosphating. Alternative finishes, such as nickel plating, etc., are available upon request.



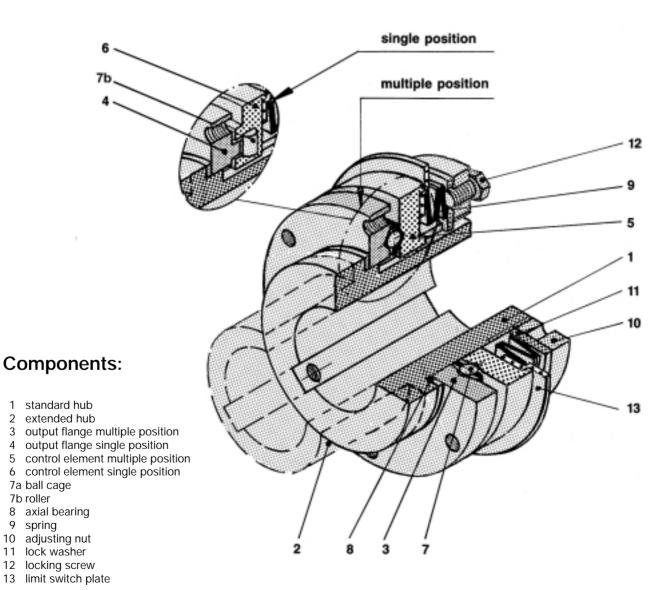
OPTI torque are available in two basic types:

OPTI torque multiple position clutch - for immediate re-engagement

The 24 balls in the OPTI torque multiple position clutch ratchet from one set of detents to the next during an overload. The multiple position OPTI torque therefore immediately and automatically re-engages, as soon as the overload has been cleared. Residual torque transmitted during an overload is substantially lower than the pre-set torque.

OPTI torque single position clutch - for timing and sequencing

By utilizing 6 unequally spaced rollers, the OPTI torque single position clutch automatically re-engages after one full revolution, once the overload has been cleared. As re-engagement is at the exact position of disengagement, timing and/or sequencing within the machine is maintained. Residual torque transmitted in disengaged position is substantially lower than the pre-set torque.



3



Selection Procedure:

OPTI torque's adaptability makes selection easy.

Two basic parameters to be considered:

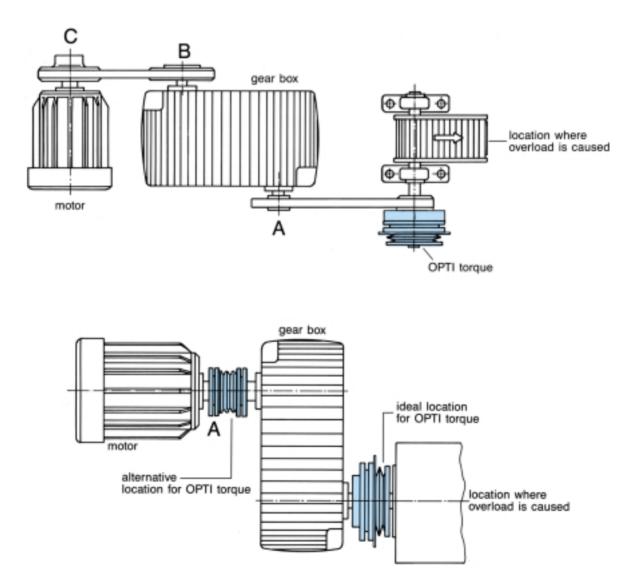
 Torque: It is essential to determine the torque at the point where OPTI torque will be mounted.

The torque should be based on allowable torque for the drive components. Alternatively torque can be calculated from the motor horsepower and operating speed.

Remember to consider peak torques due to start-up or other operating conditions that should not lead to disengagement of clutch. * Shaft diameter: The overlaps in torque ranges from one size OPTI torque to the next allow different size units to be utilized for the same torque requirement. The determining factor then becomes shaft diameter.

Location of OPTI torque:

The most effective location for OPTI torque is as close as possible to the potential trouble spot or the drive component which must be protected. Keep in mind the more inertia that is disengaged, results in less engery that can cause damage. The figures below show the recommended locations for OPTI torque in two typical drive arrangements. Alternate locations A, B and C provide less effective protection, especially when large speed reductions occur beyond the OPTI torque.



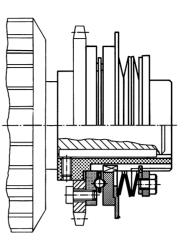
4

OPTI torque

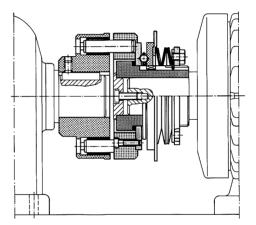


Overload protection for virtually every application

Narrow drive elements such as this "A-plate" sprocket are easily mounted on the standard hub of the OPTI torque, making both a compact and economic package.

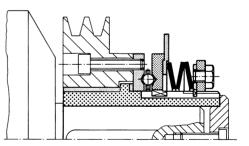


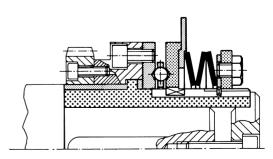
Combined with a flexible coupling, the OPTI torque connects drive and driven shafts, accomodating angular, axial and radial shaft misalignments, while also providing overload protection.



The extented hub and integral bushing of the OPTI torque makes it ideally suited for wider drive elements, such as this pulley. With the OPTI torque installed with the pulley inward, overhung load on the drive shaft is minimized, and easy access is provided for torque adjustments.

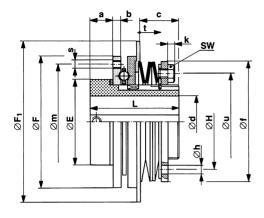
Designs for small drive elements. For use with sprockets, gears, pulleys, etc. with small pitch diameters.



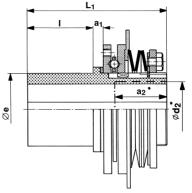




Type 460._1_.0 OPTI torque with standard hub



Type 460._1_.1 OPTI torque with extended hub



*Counterbore a2/Ød2 only with size 4

All other dimensions same as type 460.___.0.

Please notice that all threads for set screws as shown above are provided only when ordered finish bored.

Technical data and Dimensions

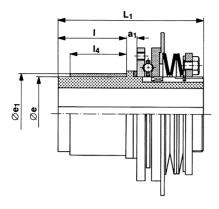
					torque ranges				
size	dim.		multiple pos	sition clutch		si	ngle position clu	utch	max. speed
5120	unn.	type 46410	type 46510	type 46610	type 46710	type 46415	type 46515	type 46615	rpm
0	lbf x in Nm	26 – 53 3 – 6	53 – 106 6 – 12	106 – 221 12 – 25	221 – 354 25 – 40	53 – 106 6 – 12	106 – 221 12 – 25	221 – 354 25 – 40	500
1	lbf x in Nm	53 – 106 6 – 12	106 – 221 12 – 25	221 – 442 25 – 50	442 – 708 50 – 80	106 – 221 12 – 25	221 – 442 25 – 50	442 – 708 50 – 80	500
2	lbf x in Nm	142 – 265 16 – 30	265 – 531 30 – 60	531 – 1062 60 – 120	1062 – 1770 120 – 200	265 – 531 30 – 60	531 – 1062 60 – 120	1062 – 1770 120 – 200	500
3	lbf x in Nm	265 – 531 30 – 60	531 – 1062 60 – 120	1062 – 1770 120 – 200	1770 – 2655 200 – 300	531 – 1062 60 – 120	1062 – 1770 120 – 200	1770 – 2655 200 – 300	500
4	lbf x in Nm	354 – 796 40 – 90	796 – 1770 90 – 200	1770 – 3363 200 – 380	3363 – 5753 380 – 650	442 – 1328 50 – 150	1328 – 3098 150 – 350	3098 – 5753 380 – 650	500

		stroke of flange a switch	nd limit	а	a ₁	a ₂	b	type 4610	type 4615	d _{min}	d _{max}	d _{1 min}	d _{1 max}	d ₂
size	dim.	multiple position clutch		u	-1	-2	5	С	С	-min	-max	- 1 min	~1 max	
0	in mm	0.047 1,2	0.047 1,2	0.452 11,5	0.157 4		0.197 5	0.854 21,7	0.834 21,2	0.375 9	0.8125 20	0.437 11	1.187 30	-
1	in mm	0.079 2,0	0.059 1,5	0.649 16,5	0.177 4.5	-	0.236 6	0.846 21,5	0.838 21,3	0.4375 12	1 25	0.5 12	1.625 42	
2	in mm	0.090 2,3	0.075 1,9	0.649 16,5	0.216 5.5	-	0.236 6	1.075 27,3	1.083 27,5	0.5625 15	1.375 35	0.625 15	1.625 42	
3	in mm	0.102 2,6	0.087 2,2	0.866 22	0.275 7		0.275 7	1.330 33,8	1.327 33,7	0.75 20	1.75 45	0.75 20	2.312 60	
4	in mm	0.102 2,6	0.087 2,2	0.866 22	0.551 14	2.362 60	0.314 8	1.575 40	1.650 41,9	1 25	2.165 55	1 25	2.312 60	2.204 56

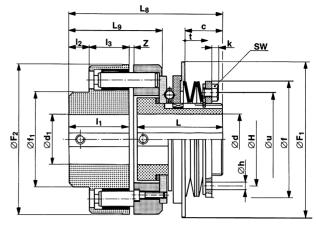


Type 460._1_.2

OPTI torque with integral bushing



Type 462._1_.0 OPTI torque combined with flexible coupling



All other dimensions same as type 460._1_.0.

Please notice that as shown above all threads for set screws are provided only when ordered finish bored.

Technical Data and Dimensions

size	dim		Er	1) 18	e _{h7}	e ₁ 1)	F _{h8}		F ₁	F ₂	f	f ₁	н		h	k
0	in mr	۱		385 34	1.1811 30	1.338 34	2.165 55		.150 80	3.150 80	1.653 42	1.96 50			0.118 3	0.019 ²⁾ 0,5 ²⁾
1	in mn	n		322 4	1.3779 35	1.535 39	2.755 70		.937 100	4.133 105	2.421 61,5	2.55 65	9 1.90 50		0.197 5	0.051 ²⁾ 1,3 ²⁾
2	in mn	n		409 52	1.9685 50	2.165 55	3.543 90		.724 120	4.133 105	3.169 80,5	2.55 65	9 2.6		0.236 6	0.118 3
3	in mn	n		527 '5	2.5590 65	2.755 70	4.527 115		.511 140	5.314 135	4.153 105,5	3.34 85	6 3.30 84		0.236 6	0.216 5,5
4	in mn	n		401 95	2.9527 75	3.149 80	5.314 135		.692 170	6.299 160	5.137 130,5	3.54 90			0.275 7	0.216 5,5
size	dim.	L	-	L ₁	L ₈	L9	I	I ₁	I ₂	I ₃	I ₄	m	s	u	SW	Z
0	in mm	1.9 5	68 0	3.287 83,5	3.445 87,5	2.007 51	1.614 41	1.181 30	0.27	5 0.905 23	1.181 30	1.811 46	6x10-24 6xM5	1.456 37	0.078 ²⁾ 2 ²⁾	0.157 4
1	in mm	2.2 5		3.700 94	4.074 103,5	2.559 65	1.929 49	1.653 42	0.393	3 1.259 32	1.574 40	2.322 59	6x10-24 6xM5	1.968 50	0.118 ²⁾ 3 ²⁾	0.157 4
2	in mm	2.5 6		4.251 108	4.389 111,5	2.559 65	2.125 54	1.653 42	0.393 10	3 1.259 32	1.574 40	3.070 78	6x1/4-20 6xM6	2.637 67	0.393 10	0.157 4
3	in mm	3.1 8		4.999 127	5.551 141	3.307 84	2.401 61	2.165 55	0.748 19	3 1.417 36	1.968 50	3.937 100	6x1/4-20 6xM6	3.307 84	0.511 13	0.157 4
4	in mm	3.6 9		6.299 160	6.338 161	3.622 92	2.952 75	2.165 55	0.66 ⁰ 17	9 1.496 38	2.362 60	4.645 118	6x5/16-18 6xM8	3.819 97	0.511 13	0.236 6

Order example:

To be included when ordering, please state:	size	Туре	bore Ø d H7	bore Ø d_1^{H7}	Examples: 2/460.640.0/1 1/2 in
Order No:		46			1/462.515.0/20mm/15 mm For limit switch details please refer to page 11.
0 ÷ 4 → OPTI torque standard0 → OPTI torque with flexible coupling2 → * low torque range					 according to clutch size according to clutch size 0 standard hub 1 extended hub 2 with integral bushing 0 multiple position clutch 5 single position clutch

* See technical data, torque ranges

please see page 8 for machining of drive elements
 hexagon socket bolt DIN 7991
 not with single position clutch

In accordance with our established policy to constantly improve our products, the specifications contained herein are subject to change without notice.



Installation

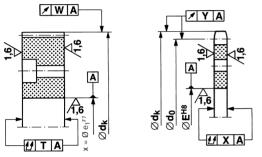
Mounting drive elements:

The drive element (sprocket, pulley, gear, etc.) is bolted to the output flange of the OPTI torque before installing on the shaft. The support required for the drive element is dependent upon which hub configuration is selected, and the drive element itself.

Standard hub (page 6): A narrow drive element, i. e.: an "A-plate" sprocket, is bolted to the output flange and supported directly on the hub. This arrangement is not recommended for applications with high radial loads or frequent overloads.

Machining of drive elements

(surface finish given in μ m; 1.6 μ m = 63 μ IN / 3.2 μ m = 126 μ IN)



1 0	Data for machining drive elements for OPTI torque
1,6	

size	٦	r	v	V)	(١	(
3120	in	mm	in	mm	in	mm	in	mm
0	.0019	0,05	.0019	0,05	.0039	0,1	.0059	0,15
1	.0019	0,05	.0019	0,05	.0039	0,1	.0059	0,15
2	.0019	0,05	.0019	0,05	.0039	0,1	.0059	0,15
3	.0031	0,08	.0031	0,08	.0059	0,15	.0078	0,2
4	.0031	0,08	.0031	0,08	.0059	0,15	.0078	0,2

Extended hub (page 5): For wider drive elements, the drive elemnt is

bolted to the output flange. Support of the drive element is either by a

customer provided bearing or bushing, or one that is integral to the

It is essential to ensure that no axial forces are applied to the output

flange by the drive element, i. e. by misaligned belts or chains, or

OPTI torque, as in the models 460.___.2 and 460.___.5.

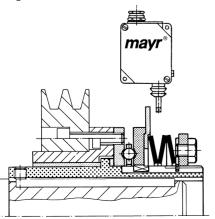
improper installation of the drive element.

Single plate (A-plate) sprockets for OPTI torque

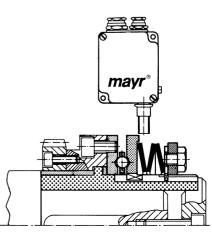
									SI	nalle	est p	ossi	ble r	umb	oer o	f tee	th										spro	ckets	
limiter	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	pitch	RC #	wi in	dth mm
	-	-	-	-	-	-	-	-	-	-	0	0	0	0	0	0-1	0-1	0-1	0-1	0-1	0-1	0-2	0-2	0-2	0-2	3/8″	35	.168	4,3
torque	-	-	-	-	-	0	0	0	0	0-1	0-1	0-1	0-1	0-1	0-2	0-2	0-2	0-2	0-2	0-2	0-3	0-3	0-3	0-3	0-4	1/2″	40	.284	7,2
of to	-	-	0	0	0	0-1	0-1	0-1	0-1	0-2	0-2	0-2	0-2	0-2	0-3	0-3	0-3	0-3	0-4	0-4	0-4	0-4	0-4	0-4	0-4	5/8 [~]	50	.343	8,7
size o	0	0	0	0-1	0-1	0-1	0-2	0-2	0-2	0-2	0-3	0-3	0-3	0-4	0-4	0-4	0-4	0-4	0-4	0-4	0-4	0-4	0-4	0-4	0-4	3/4″	60	.459	11,6
S	0-1	0-1	0-1	0-2	0-2	0-2	0-3	0-3	0-4	0-4	0-4	0-4	0-4	0-4	0-4	0-4	0-4	0-4	0-4	0-4	0-4	0-4	0-4	0-4	0-4	1″	80	.575	14,6
	0-2	0-2	0-2	0-3	0-4	0-4	0-4	0-4	0-4	0-4	0-4	0-4	0-4	0-4	0-4	0-4	0-4	0-4	0-4	0-4	0-4	0-4	0-4	0-4	0-4	1 1/4″	100	.692	17,5

Installation on shaft

All OPTI torque hubs are bored and keyed through, and once installed on the shaft are typically held axially by means of a set screw, as shown in the figure below.



Preferably OPTI torque should be held on the shaft by means of a clamp plate, as shown in the figure below.



OPTI torque



Disc spring layer configuration

Only the correct disc spring configuration guarantees that the torques mentioned in the catalogue can be achieved and that the torque can be adjusted without problems.

The disc spring configuration is different and depends on the size and type of clutch.

Size 0:		Size 1-4:	
Type 46415	1x helical layer	Type 4641	3x single layer
Type 4651	5x single layer	Type 4651	3x single layer
Type 4661	5x double layer	Type 4661	3x single layer
Type 46710	3x triple layer	Type 46710	3x double layer

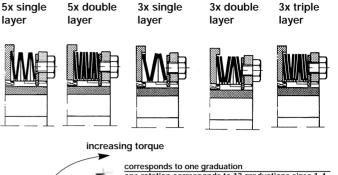
Torque adjustment

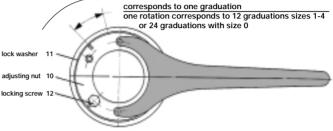
The disengaging torque is set by turning the adjusting nut. Clockwise rotation of the adjusting nut (when viewed as shown) increases the torque setting, and counter-clockwise rotation decreases the torque setting.

Initial torque setting

Prior to initially setting the disengaging torque, check that the thread on the adjusting nut and hub, and contact surfaces of the adjusting nut and lockwasher have been greased. Then proceed as follows:

- * Manually tighten the adjusting nut until it contacts the discs springs
- * Continue turning until the notches in lock washer are in line.



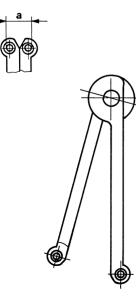


- * Using a face wrench, tighten the adjusting nut the required number of graduations corresponding to the desired torque setting, as shown in the setting diagrams.
- * When the notches in the adjusting nut and lock washer are again in line, the locking screw can the be installed.

Setting example

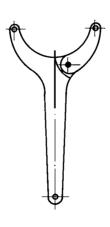
A size 3, type 4__.610._ OPTI torque is to be set at 1500 lbs-in.

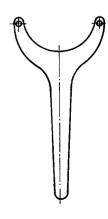
From the setting diagram (included with every clutch) the required number of graduations is 15. Following the above instructions, the adjusting nut is tightend 15 graduations.



wrench 1 a = .368 [in]

OPTI torque size	wrench Type
0	1
1	3
2	2
3	2
4	2

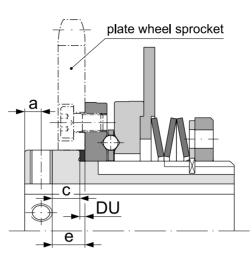




wrench 2

wrench 3





		Recomm	ended set s	crew sizes	and position	n of plate w	heel sprock	ket	
oizo	set screw	dimens	sion "a"	dimens	sion "c"	dimen	sion "e"	DU	disc
size	metric	mm	inch	mm inch		mm	inch	mm	inch
0	M4	3	0.118	5	0.197	6,5	0.256	1,5	0.059
1	M6	4,5	0.177	7,5	0.295	9	0.354	1,5	0.059
2	M6	4,5	0.177	7,5	0.295	9	0.354	1,5	0.059
3	M8	6	0.236	10	0.394	12	0.472	2	0.079
4	M8	6	0.236	10	0.394	12	0.472	2	0.079

		F	Recommend	ded set scre	ew sizes and	d position (ANSI)		
	set screw	dimens	sion "a"	dimens	sion "c"	dimen	sion "e"	DU	disc
size		mm	inch	mm	inch	mm	inch	mm	inch
0	10-32 UNF	3	0,118	4,6	0.181	6,1	0.240	1,5	0.059
1	1/4-20 UNC	4.5	0.177	7,3	0.287	8,8	0.346	1,5	0.059
2	5/16-18 UNC	4.5	0.177	6,5	0.256	8	0.315	1,5	0.059
3	5/16-18 UNC	6	0.236	10	0.394	12	0.472	2	0.079
4	3/8-16 UNC	6	0.236	9,2	0.362	11,2	0.441	2	0.079

	Standard k	eyways used		То	Tolerance chart for finish bore				
DIN 688	5 (mm)	ANSI (i	n.)	dim.	shaft diameter	ł			
bore	keyway	bore	keyway	mm	10 – 18				
17 – 22	6 x 2,8	5/8 – 7/8	3/16 x 3/32	in	0.39 – 0.7	+			
23 – 30	8 x 3,3	15/16 – 1 – 1/4	1/4 x 1/8	mm	20 - 30	+			
31 – 38	10 x 3,3	1 – 5/16 – 1 – 3/8	5/16 x 5/32		20 - 30				
39 – 44	12 x 3,3	1 – 7/16 – 1 – 3/4	3/8 x 3/16	in	0.7 – 1.2	+ (
45 – 50	14 x 3,8	1 – 13/16 – 2	1/2 x 1/4	mm	30 – 50	+			
51 – 55	16 x 4,3	2 – 1/16 – 2 1/8	1/2 x 1/4	in	1.2 – 2	+			



Application

Monitoring of mechanical movements and final positions. Control switch for electronic and mechanical sequences. Measuring of axial disengaging movements, for example in connection with EAS[®]-clutches.

Function

The pre positioned contact is unloaded by actuating the control lever: Open contacts 11-14 (21-24), close 11-12 (21-22).

Design

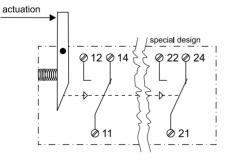
The micro switch fitted into an aluminium die cast housing is actuated by a control lever. Operation is only possible in one direction.

The limit switch is fastened with M4 cap screws via two screw-on brackets attached diagonally.

Technical data

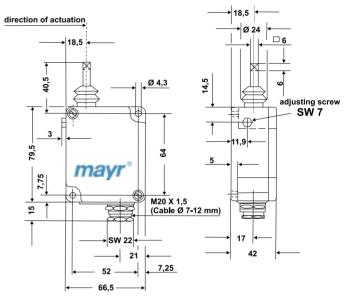
Contact type	1 change-over contact (special design: 2 change-over contacts)			
Switching capacity	250 VAC / 15 A (with 2 contacts: 10A) 24 VDC / 6 A 60 VDC / 1,5 A 250 VDC / 0,2 A min. 12 VDC/10 mA			
Contact material	AgCdO 90/10			
Switching frequency Ambient temperature Protection Weight	max. 200 switching operations/min -10 °C up to +85 °C IP 54 275 g			
Switch travel setting	By the adjusting screw (SW 7) arranged laterally the zero shift is possible to right or left by max. 5 mm			
Switch travel	Pre-travel min. 0,15 to 0,5 mm Over-travel: max. 10 mm, depending on the zero shift			
Special types	On request different control lever lengths as well as a design with 2 change-over contacts are possible			

Electrical connection





Dimensions (mm)



To be included when ordering, please state:	Туре	
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